

(12) PATENT APPLICATION PUBLICATION

(21) Application No.202441014822 A

(19) INDIA

(22) Date of filing of Application :28/02/2024

(43) Publication Date : 08/03/2024

(54) Title of the invention : BIOINSPIRED INCH WORM WALL CLIMBING ROBOT WITH HYBRID MECHANISM

(51) International classification :B62D0057024000, H02N0002020000, B62D0055265000, A61K0036600000, B25J0009000000
(86) International Application No :NA
Filing Date :NA
(87) International Publication No : NA
(61) Patent of Addition to Application Number :NA
Filing Date :NA
(62) Divisional to Application Number :NA
Filing Date :NA

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(57) Abstract :

The main theme of the Project is to design and fabricate a bioinspired wall climbing robot which mimics the motion of an inchworm with hybrid mechanism (both pneumatics and electromagnetic solenoids). These wall climbing robot reduces the human effort and risk performing high altitude jobs and also working at radiation prone zone in industries. Accompanied Drawing [FIG. 1] [FIG. 2] [FIG. 3] [FIG. 4]

No. of Pages : 10 No. of Claims : 3